**19EC3102– DIGITAL SIGNAL PROCESSING**

(Common to ECE and EEE)

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| **Course category:** | | Program core | | **Credits:** | 3 |
| **Course Type:** | | Theory | | **Lecture - Tutorial - Practical:** | 2 - 1 - 0 |
| **Prerequisite:** | | Signal & System, Fourier transform, Laplace Transform & Z transform | | **Sessional Evaluation :**  **External Evaluation:**  **Total Marks:** | 40  60  100 |
| **Course**  **Objectives** | Students undergoing this course are expected tounderstand: | | | | |
| 1. The basic concepts and analytical methods of Z-transform. 2. The various DFT & FFT algorithms. 3. The techniques and tools for digital filter structures. 4. The design of FIR filters. 5. The various IIR filters. 6. The truncation and Rounding errors, Quantization noise | | | | |
| **Course Outcomes** | Upon successful completion of the course , the students will be able to: | | | | |
| CO1 | | Explain the concept of Z-transform, its properties and understand the concept of discrete and fast Fourier trans forms. | | |
| CO2 | | Understand the concept of IDFT and IZT | | |
| CO3 | | Apply the Concept of FIR ,IIR Structures and frequency domain filter models | | |
| CO4 | | Design Parallel and cascade structure and Butterworth, Chebyshev filters. | | |
| CO5 | | Design FIR filter using Fourier series method and understand the concept of fixed point and floating-point representation. | | |
| CO6 | | Understand limit cycle oscillations concept and windowing technique. | | |
| **Course**  **Content** | **UNIT – I**  **REVIEW OF Z-Transforms:** Z-transform and Inverse Z-Transform, Theorems and Properties, system function, Fourier representation of finite duration sequences.  **UNIT – II**  **DISCRETE & FAST FOURIER TRANSFORM**: DFT, properties of DFT, FFT, FFT algorithms, Use of DFT for fast computation of convolution, IDFT.  **UNIT – III**  **DIGITAL FILTER STRUCTURES:** Basic FIR structures, IIR structures: Direct form-I, Direct form-II, Parallel form, Cascade form.  **UNIT – IV**  **DESIGN OF IIR FILTERS:** Analog filter approximations – Butterworth and Chebyshev, Design of IIR Digital Filters from Analog Filters, Impulse Invariant and Bilinear Transformation Method.  **UNIT – V**  **DESIGN OF FIR FILTERS**: Introduction to FIR filter, Methods of FIR filters: Fourier series method, Windowing, Sampling.  **UNIT-VI**  **FINITE WORDLENGTH EFFECTS**: Fixed point and floating point number representations – Truncation and Rounding errors – Quantization noise – coefficient quantization error – Product quantization error – Overflow error – Round off noise power – limit cycle oscillations due to product round off and overflow errors. | | | | |
| **Text Books and Reference Books** | **TEXTBOOKS:**   1. Digital Signal Processing A.V Oppenheim and R.W. Schafer, Prentice – Hall of India. 2. Digital Signal Processing, S. Salivahanam – TMH. 3. Digital Signal Processing Computer Base Approach, S.K. Mitra – Tata McGraw-Hill (III)   **REFERENCES BOOKS :**   1. Digital Signal Processing, P. Ramesh Babu, Scitech Publications. 2. Digital Signal Processing, John G Proakis and monolokis – Wiley Eastern Economy edition. | | | | |
| **E-Resources** | 1. <http://nptel.ac.in/courses> 2. <https://dspace.mit.edu/handle/1721.1/57007> 3. http://dl.acm.org/citation.cfm?id=562622 | | | | |

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| **Contribution of Course Outcomes towards achievement of Program Outcomes** | | | | | | | | | | | | | | |
|  | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | 2 | 3 | 3 |
| CO2 | 3 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | 2 | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 1 | 1 | - | - | 1 | - | - | 2 | 2 | 3 |
| CO4 | 3 | 3 | 2 | 2 | 1 | 1 | - | - | - | - | - | 2 | 2 | 3 |
| CO5 | 3 | 3 | 2 | 2 | 1 | 1 | - | - | 1 | - | - | 2 | 3 | 2 |
| CO6 | 3 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | 2 | 3 | 2 |